## Contents


**1 Introduction** 1

1.1 DC Motors 1

1.1.1 Advantages Of DC Motors 1

1.1.2 Disadvantages Of DC Motors 2

1.2 AC Motors 2

1.2.1 Advantages Of AC Motors 2

1.2.2 Disadvantages Or Limitations Of AC Motors 3

1.2.3 Permanent Magnet Synchronous Motors 3

1.3 Brush Less DC Motors (BLDCM) 6

1.3.1 Rotor 9

1.3.2 Hall Sensors 10

1.3.3 Construction Of BLDC Motor 10

1.3.4 Applications Of BLDC Motors 14

1.3.5 Advantages of BLDC Motors 15

1.3.6 Disadvantages Of BLDC motors 15

1.4 Control strategies for speed control of a general motor 18

1.5 PID Controller 18

1.5.1 Fuzzy Logic Controller 22

1.5.2 Fuzzification 25

1.5.3 Membership Functions 25

1.5.4 Fuzzification Methods 27

1.5.5 Knowledge Base 30

1.5.6 Inference Engine 31

1.5.7 Fuzzy Rule Base 32

1.5.8 Defuzzification 38

1.5.9 Assumptions in a Fuzzy control System Design 42

1.6 Outline of the Ph.D. Thesis: 44

**2 Formulation Of The Problem** 45

2.1 Block diagram of Speed Control of BLDC Motor and its working 45

2.1.1 Hardware Components Used in Speed Control System 46

2.1.1.1 Analog input card (SCXI-1122) 48

2.1.1.2 Analog output card (SCXI-1124) 49

2.1.1.3 DAQ (Data Acquisition) Board 49

2.1.1.4 Pulse width modulation (PWM) controller 52

2.1.1.5 Driver Circuit 54

2.1.2 Software

2.1.2.1 LabVIEW 54

2.1.2.2 Front panel 55

2.1.2.3 Block diagram 55

2.1.2.4 Tools palette 57

2.1.2.5 Controls palette 57

2.1.2.6 Functions palette 57

2.1.2.7 PID Toolkit 58

2.1.2.8 Fuzzy logic tool kit 59

2.2 Literature survey and motivation for the present work 60

2.2.1 General Literature Survey 60

2.2.2 Literature Survey on Fuzzification, Rule Base and Defuzzication 64

2.2.3 Literature Survey on the Application of PID, FLC and IFLC for the Speed Control of BLDC Motor Drives 70

2. 2.4 Literature Survey on the FLC and IFLC for the Effect of Noise/ Disturbance 79

2.3 Motivation for the Present Work 84

**3 Design and Development of PID and Auto Tuned PID Controllers** 86

3.1VI block diagram for PID control using Lab VIEW 86

3.2 Auto tuned PID controller 87
3.3 Experimental Results and Discussion 88
**4 Design and Development of FLC/AIFLC controllers** 91
4.1 Design and Development of C2ISO FLC 91
4.1.1Selection of number of Traingular membership functions 91
4.1.2 Selection of defuzzification method 93
4.1.3 Sampling rate 93
4.1.4 Experimental results and discussions 93
4.1.5 Conclusions 96
4.2 Design and development of C3ISO FLC 97
4.2.1 VI block diagram for 3ISO FLC 97
4.3 Design and development of 2 input AIFLC 97
4.3.1 VI Block diagram for 2ISO AIFLC 99
4.4 Design and development of C3ISO AIFLC 99
4.5 Desired speed 100
4.6 Load variations 100
4.7 Brake applications 100
4.8 Effect of noise on FLC/ AIFLC/(C2ISO and C3ISO) 104
4.8.1 Design and development of FLC and AIFLC (C2ISO andC3ISO) for studying the effect of noise on speed control of BLDC motor 104
4.8.2 Separation of Gaussian white noise using IIR filter 106
4.9 Design and development of controllers for suppressing Gaussian white noise introduced in FLC and AIFLC (C2ISO and C3ISO) using IIR filter 107
5. **Results and Discussion**
5.1 PID and auto tuned PID controllers 111
5.2 Fuzzy Logic Controller (FLC) and Auto Integrated Fuzzy Logic Controller (AIFLC) 112

5.3 Gaussian white Noise 118

5.3.1 2 ISO FLC 118

5.3.2 3 ISO FLC 118

5.3.3 2ISO AIFLC 119

5.3.4 3 ISO AIFLC 119

5.4 I I R filter 119

**6 Conclusions**

6.1 PID and auto tuned PID controllers 121

6.2 Fuzzification and defuzzification methods 121

6.3 MISO FLC/AIFLC 122

6.4 Brake application 123

6.5 Load variations 123

6.6 Effect of Gaussian white noise 123

6.7 IIR (chebyshev) filter 124

6.8 Scope of the future work 125

**Appendix**

**Results of speed control of BLDC motor**

**List of Abbreviations**

**Photographs of BLDC motor**