

STUDIES ON STABILITY AND OPTIMIZATION
OF ROBUST CONFIGURATIONS USED FOR
TRAINING OF PARALYSED PERSON THROUGH
DYNAMIC PARAMETER CONSIDERATION

ALAVALA CHENNAKESAVA REDDY



THESIS SUBMITTED TO JNTU UNIVERSITY
FOR THE AWARD OF THE DEGREE OF
DOCTOR OF PHILOSOPHY
IN ELECTRICAL ENGINEERING

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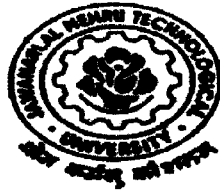
**STUDIES ON SYNTHESIS AND OPTIMIZATION OF
ROBOTIC CONFIGURATIONS USED FOR TRAINING
OF PARALYZED PERSON THROUGH
DYNAMIC PARAMETER CONSIDERATION**

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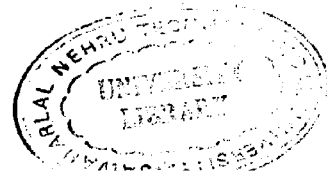


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